Understanding large-scale atmospheric and oceanic flows with layered rotating shallow water models

V. Zeitlin,

Non-homogeneous Fluids and Flows, Prague, August 2012

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Ingredients

- Multi-layer shallow-water models;
- Exhaustive linear stability analysis by the collocation method;
- High-resolution numerical simulations of nonlinear evolution with new-generation finite-volume code.

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Workflow

- Choose a model: 1.5 or 2 -layer (or more!);
- Choose bathymetry;
- Choose balanced profiles of velocity/interface;
- Analyse linear stability: unstable modes, growth rates;
- Initialise nonlinear simulations with the unstable modes, study saturation;
- Look how instabilities manifest themselves in initial-value problem.

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Typical configuration



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RSW equations with coast (no bathymetry)

Equations of motion:

$$\begin{array}{rcl} u_t + uu_x + vu_y - fv + gh_x &=& 0, \\ v_t + uv_x + vv_y + fu + gh_y &=& 0, \\ h_t + (hu)_x + (hv)_y &=& 0. \end{array}$$

$$H(y) + h(x, y, t) = 0$$
, $D_t Y_0 = v$ at $y = Y_0$, (2)

where $Y_0(x, t)$ is the position of the free streamline, D_t is Lagrangian derivative.

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Balanced flows: u = U(y), v = 0, and h = H(y), $U(y) = -\frac{g}{f}H_y(y)$

exact stationary solution.



Figure: Examples of the basic state heights (left) and velocities (right) for constant PV flows with $U_0 = -sinh(-1)/cosh(-1)$ (thick line), $U_0 = 1/2$ (dotted) and a zero PV flow (dash-dotted)

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Non-dimensional linearized system:

$$u_t + Uu_x + vU_y - v = -h_x,$$

$$v_t + Uv_x + u = -h_y,$$

$$h_t + Uh_x = -(Hu_x + (Hv)_y).$$

Linearized boundary conditions:

$$Y_0 = -\frac{h}{H_y}\Big|_{y=0},$$

• continuity equation evaluated at y = 0.

The only constraint is regularity of solutions at y = 0.

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PV of the mean flow

$$Q(y)=\frac{1-U_y}{H(y)},$$

Geostrophic equilibrium \Rightarrow

$$H_{yy}(y) - Q(y)H(y) + 1 = 0, \ \text{with} egin{cases} H(0) = 0 \ H_y(0) = -U_0, \end{cases}$$

 $U(0) = U_0$ is the mean-flow velocity at the front.

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Figure: Stability diagram in the $(\frac{U_0}{fL}, k)$ plane for the constant PV current. Values of the growth rates in the right column.

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Dispersion diagram: stable flow



Figure: Dispersion diagram for $U_0 = -sinh(-1)/cosh(-1)$ and $Q_0 = 1$.

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Dispersion diagram: unstable flow



Figure: Dispersion diagram for $U_0 = 0.5$ and $Q_0 = 1$. Crossings of the dispersion curves in the upper panel correspond to instability zones in the lower panel. Lecture 3: Applications to the ocean, density-driven coastal currents

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The most unstable mode: Kelvin-Frontal resonance



Figure: Height and velocity fields of the most unstable mode k = 3.5.

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Saturation of the primary instability



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Figure: Height and velocity fields of the perturbation at t = 0 (left) and t = 30 (right). Kelvin front is clearly seen at the bottom of the right panel.

Kelvin wave breaking



Figure: Evolution of the tangent velocity at y = -L (at the wall) for t = 0, 2.5, 5, 7.5, 10, 12.5, 15, 17.5, 20, 22.5 (from lower to upper curves)

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Secondary instability



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Figure: Height and velocity fields of the secondary perturbation at t = 335, t = 500 (right).

Reorganization of the mean flow



Figure: Evolution of the mean zonal height (left) and mean zonal velocity (right): Initial state t = 0 (dashed line), primary unstable mode saturated at t = 40 (dash-dotted line), late stage t = 300 (thick line).

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Stability diagram of the reorganized flow



Figure: Dispersion diagram of the eigenmodes corresponding to the basic state profile of the flow at t = 335, at the beginning of the secondary instability stage (see Fig. 9).

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Most unstable mode of the reorganized flow



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Figure: Height and velocity fields of the most unstable mode of figure 10 for $k = k_0$. Only one wavelenght is plotted. Note the similarity with the mode observed in the simulation, Fig. 8

Instability in Cauchy problem



Figure: y - c diagram of the height field at t = 45 of the development of initially localised perturbation (dotted) for linearly stable (upper) and unstable (lower) current. Phase-locking of frontal and Kelvin waves in the lower panel

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Equations of motion

$$\begin{array}{rcl} D_j u_j - f v_j &=& -\frac{1}{\rho_j} \partial_x \pi_j, \\ D_j v_j + f u_j &=& -\frac{1}{\rho_j} \partial_y \pi_j, \\ D_j h_j + \nabla \cdot (h_j \mathbf{v_j}) &=& \mathbf{0}, \end{array}$$

j = 1,2: upper/lower layer, (*x*, *y*), $h_j(x, y, t)$ - depths of the layers, π_j , ρ_j - pressures, densities of the layers,

$$abla \pi_j =
ho_j g \nabla (s^{j-1} h_1 + h_2), \ s =
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ho_2.$$

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Stationary solutions

Balanced flow with depths $H_i(y)$ and velocities $U_i(y)$:

$$\partial_y H_j = (-1)^{j-1} \frac{f}{g'} (U_2 - s^{j-1} U_1),$$
 (10)

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Linearization/nondimensionalization:

$$\partial_{t}u_{j} + U_{j}\partial_{x}u_{j} + v_{j}\partial_{y}U_{j} - v_{j} = -\partial_{x}(s^{j-1}h_{1} + h_{2}),$$

$$\partial_{t}v_{j} + U_{j}\partial_{x}v_{j} + u_{j} = -\partial_{y}(s^{j-1}h_{1} + h_{2}),$$

$$\partial_{t}h_{j} + U_{j}\partial_{x}h_{j} + H_{j}\partial_{x}u_{j} = -\partial_{y}(H_{j}v_{j}).$$
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Boundary conditions

- Upper layer: same as in 1.5-layer case,
- Lower layer: for harmonic perturbations

$$u_j(x,y), v_j(x,y), h_j(x,y)) = (ilde{u}_j(y), ilde{v}_j(y), ilde{h}_j(y)) \; e^{i(kx-\omega t)}$$

Filtering of outer inertia-gravity waves, decay condition:

$$\partial_y(sh_1 + h_2) = -k(sh_1 + h_2)$$
 at $y = 0$.

Key parameters:

 U_0 , the non-dimensional velocity of the upper layer at the front location y = 0, equivalent to Rossby number, aspect ratio $r = H_1(-1)/H_2(-1)$, and stratification $s = \rho_1/\rho_2$.

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Configurations considered:

- Bottom layer: initially at rest $(U_2 = 0)$,
- Upper layer: with constant PV.

Two classes of flows: barotropically stable/unstable, i.e. stable/unstable in the 1.5 - layer limit.

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Barotropically stable case



Figure: Dispersion diagrams for s = .5. (a) r = 10, (b) r = 2, (c) r = 0.5. Horizontal scale of the bottom panel shrinked to show short-wave KH instabilities.

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Barotropically unstable case



Figure: Dispersion diagrams for s = 0.5 and for $R_d = 1$. (*a*) r = 10, (*b*) r = 5, (*c*) r = 2. The horizontal scale of the panels shrinked to show short-wave KH instabilities.

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Figure: Typical unstable modes(left to right, top to bottom): KF1, RF, RP, PF.

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Scenario of development of the baroclinic RF instability as follows from DNS

- Upper layer: frontal wave evolves into a series of monopolar vortices at certain spacing due to vortex lines clipping and reconnection following formation of Kelvin fronts
- Lower layer: Rossby wave develops a series of vortices of alternating signs
- Lower-layer dipoles drive the vortex out of the shore and are at the origin of the detachment.

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Figure: Levels of $h_1(x, y, t)$ in the upper layer (left) and isobars of $\pi_2(x, y, t)$ in the lower layer (right) at t = 150 and 200 for the development of the unstable RF mode superposed on the basic flow with a depth ratio r = 2.

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Figure: Logarithm of the kinetic energy K_{per} of the perturbation for the unstable mode in the upper layer (thick) and in the lower layer (dashed).

Kelvin front and dissipation during development of RF instability



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Figure: Before detachment: zoom of the wall region.

Structure of the detached vortex 1



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Figure: Isobars of $\pi_1(x, y, t)$ in the upper layer (white lines) and $\pi_2(x, y, t)$ in the lower layer (dark lines) at t = 250. Dark (light) background: anticyclonic (cyclonic) region.

Structure of the detached vortex 2



Figure: The x (left) and y (right) cross-sections of the detached vortex at t = 300

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Evolution of the total energy



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Figure: Levels of $h_1(x, y, t)$ in the upper layer (left) and isobars of $\pi_2(x, y, t)$ in the lower layer (right) at t = 20 and 60 for the development of the unstable RF mode superposed on the basic flow with a depth ratio r = 0.5.

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Figure: Left -logarithm of the kinetic energy of the perturbation for mode $k = k_0$ in the upper layer (solid) and in the lower layer (dashed), and for the sum of modes with $k > 10 k_0$ (dashed-dotted). Right - time-dependence of the total energy (thick line) and the dissipation rate (dashed line) for the evolution of the instability Lecture 3: Applications to the ocean, density-driven coastal currents

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Loss of hyperbolicity



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Figure: Contours of $\pi_1(x, y, t)$ (upper panel) and $\pi_2(x, y, t)$ (lower panel) with mean zonal flow filtered out at t = 20, with a depth ratio r = 0.5. The white lines indicate the boundaries of non-hyperbolic domains.

- Exhaustive linear stability analysis of coastal currents/oucropping fronts performed,
- Physical nature of all instabilities as resonances between various eigenmodes established,
- Nonlinear evolution of leading instabilities simulated with new high-resolution finite-volume code,
- An essential role of Kelvin fronts (breaking Kelvin waves) in reorganization of the flow and coherent structure formation highlighted,
- A mechanism of vortex detachment from the unstable baroclinic coastal current is identified,
- (Non-) Influence of short-scale shear instabilities understood.

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Presentation is based on

- J. Gula and V. Zeitlin, "Instabilities of buoyancy-driven coastal currents and their nonlinear evolution in the two-layer rotating shallow water model. Part 1. Passive lower layer", *J. Fluid Mech.*, 659, 69 - 93 (2010).
- J. Gula, V. Zeitlin and F. Bouchut, "Instabilities of buoyancy-driven coastal currents and their nonlinear evolution in the two-layer rotating shallow water model. Part 2. Active lower layer" *J. Fluid Mech.*, 665, 209 - 237 (2010).

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